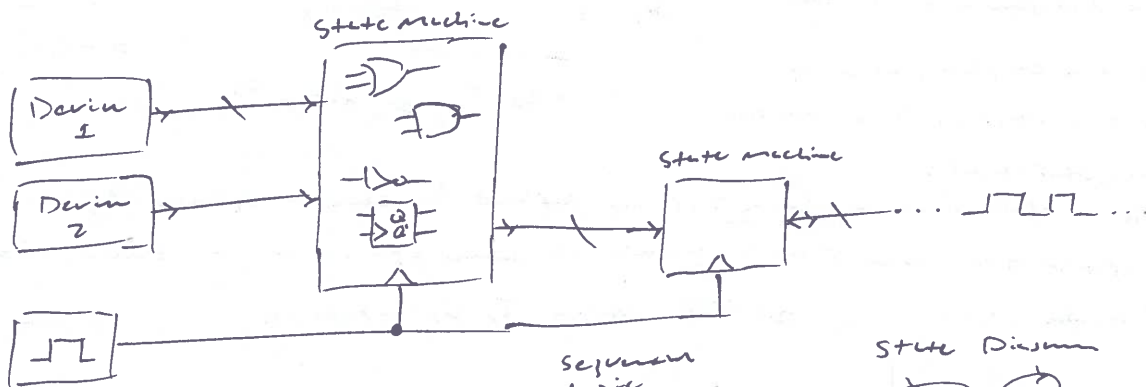


System Design

There are many ways we can represent an electronic system depending on what the device abstraction is

Digital System:

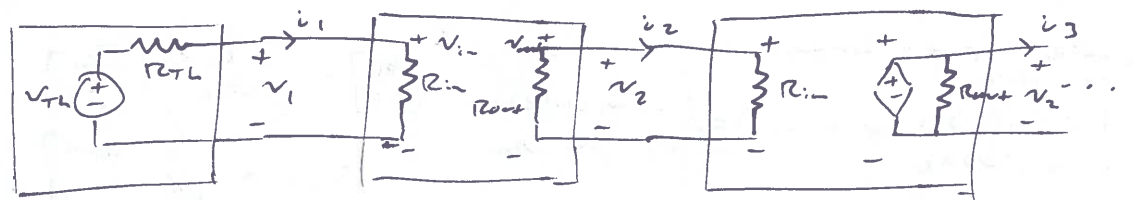
A digital system can be represented as a connection of digital blocks consisting of underlying logic gates and registers.



Characteristics:

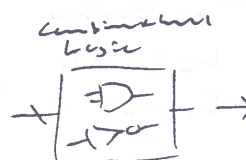
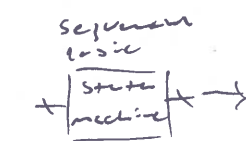
- Signals are 1s and 0s only
- Instantaneous propagation
- Connections are lumped into buses
- Usually uni-directional logic flow

Analog System:



Characteristics:

- Thevenin-Norton Abstraction
- Define/solve for voltages and currents
- Use of RLC components and analysis

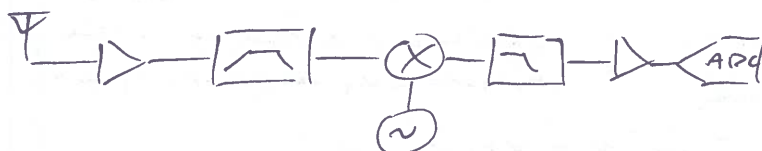


Truth Table

A	B	C	S
0	0	0	1
0	0	1	0
...	...	...	...

Using Circuit-Theory, one can abstract analog circuit blocks into a set of fundamental circuit elements, which can then be used.

RF System:

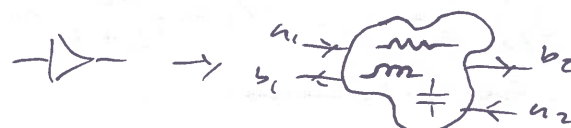


Essentially the same as the Analog System except at the sinusoidal-steady-state limit. These components are ~~represented~~ represented as lumped S-parameter matrices.

Characteristics:

- Signals are bidirectional
- Signals represented as phasors (vectors)
- Sinusoidal Steady-state (~~not transient~~) (NOT transient)

Each Device is an S-parameter matrix at one frequency, ω



$$S = \begin{bmatrix} \dots \end{bmatrix}$$

Use Phasors with directionality at a particular frequency

$$v_1^+ = v_0^+ e^{-j\omega t}, \quad v_1^- = v_0^- e^{j\omega t}, \quad \text{where } v_0^\pm = A e^{j\phi}$$

↑
Amplitude ↑
Phase

Real voltage: $V_1 = \text{Re}\{v_1^+ + v_1^-\}$ on a node

S-Parameters:

Represent an RF device
with bi-directional flow

- a_i is a complex phasor input
- b_i is a complex phasor output

$$\begin{array}{c} a_1 \rightarrow \boxed{S} \rightarrow b_2 \\ b_1 \leftarrow \leftarrow a_2 \end{array} \rightarrow \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$\vec{b} = S \vec{a}$$

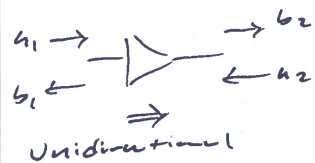
$$a_i \sim A e^{j\phi_i}, b_i \sim B e^{j\phi_i}$$

Characteristics:

- One S-parameter matrix is typically defined for one frequency ω , ω .
- Input/outputs are time-harmonic $\rightarrow$ Linear operation in Fourier Domain
- To obtain S-matrix, define outputs $\vec{b}$ by inputs $\vec{a}$

Ideal Examples:

Amplifier:



define outputs in terms
of inputs

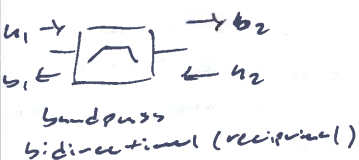
$$b_2 = G a_1 \quad \text{When } G \text{ is voltage gain.}$$

$$b_1 = 0$$

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ G & 0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}, \quad S = \begin{bmatrix} 0 & 0 \\ G & 0 \end{bmatrix}$$

$\uparrow$ Valid for signal frequency, ω

Filter:



define outputs in terms
of inputs

$$b_2 = h(\omega) a_1 \quad \text{when } h(\omega) = \begin{cases} 1, & \omega_1 < \omega < \omega_2 \\ 0, & \text{otherwise} \end{cases}$$

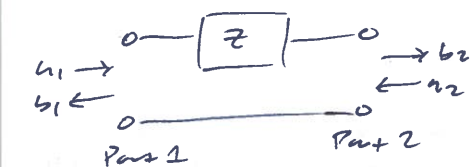
$$b_1 = h(\omega) a_2$$

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} 0 & h(\omega) \\ h(\omega) & 0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$S(\omega) = \begin{bmatrix} 0 & h(\omega) \\ h(\omega) & 0 \end{bmatrix}$$

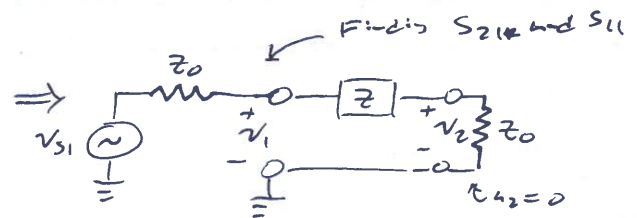
Calculating S-Parameter matrix (Passive Circuits):

Given simple series impedance, calculate S-parameter matrix, for system with Z_0 impedance.



$$\begin{aligned} a_1 &= V_1^+, & a_2 &= V_2^+ \\ b_1 &= V_1^-, & b_2 &= V_2^- \end{aligned}$$

Representing system with
Voltage/Currents



Calculate one Port at a time
by terminating all other ports.

Calculations:

Given that Port 1 has a source and Port 2 is terminated,

$$V_1^+ = \frac{1}{2} V_{S1}, \quad V_2^+ = 0 \rightarrow V_1 = V_1^+ + V_1^- = \frac{1}{2} V_{S1} + V_1^- \quad \text{and} \quad V_2 = V_2^+ + V_2^- = V_2^-$$

Use node method to find voltages V_1 and V_2 ,

$$V_1 = \frac{Z + Z_0}{2Z_0 + Z} V_{S1}, \quad V_2 = \frac{Z_0}{2Z_0 + Z} V_{S1}$$

So solve for S-Parameters:

$$\text{Recall: } b_1 = S_{11} a_1 + S_{12} a_2 \quad \text{and} \quad b_2 = S_{21} a_1 + S_{22} a_2 \rightarrow$$

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} = \left. \frac{V_1^-}{V_1^+} \right|_{V_2^+=0} = \frac{V_1 - \frac{1}{2} V_{S1}}{\frac{1}{2} V_{S1}} = \frac{Z}{2Z_0 + Z}$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} = \left. \frac{V_2^-}{V_1^+} \right|_{V_2^+=0} = \frac{V_2}{\frac{1}{2} V_{S1}} = \frac{2Z_0}{2Z_0 + Z}$$

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0}, \quad S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0}$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0}, \quad S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0}$$

Since this circuit is passive $\rightarrow$ Reciprocal
S-Parameter matrix is symmetric, $S = S^T$

$$S_{11} = S_{22} \rightarrow S = \begin{bmatrix} \frac{Z}{2Z_0 + Z} & \frac{2Z_0}{2Z_0 + Z} \\ \frac{2Z_0}{2Z_0 + Z} & \frac{Z}{2Z_0 + Z} \end{bmatrix} \checkmark$$

$$S_{21} = S_{12}$$

$$\left. \begin{array}{c} \begin{array}{c} \text{---} \boxed{Z} \text{---} \\ \text{---} \end{array} \\ \begin{array}{c} a_1 \rightarrow \\ \leftarrow b_1 \\ \text{---} \end{array} \end{array} \right\} = S = \begin{bmatrix} \frac{Z}{2Z_0 + Z} & \frac{2Z_0}{2Z_0 + Z} \\ \frac{2Z_0}{2Z_0 + Z} & \frac{Z}{2Z_0 + Z} \end{bmatrix} \rightarrow \begin{array}{l} S_{21} = S_{12} = \frac{2Z_0}{2Z_0 + Z} \text{ Power flowing through the device, input} \rightarrow \text{output} \\ S_{11} = S_{22} = \frac{Z}{2Z_0 + Z} \text{ Power reflected by the device at its inputs} \end{array}$$

Double check:

Set Z to be a capacitor (DC-Block), $Z = \frac{1}{j\omega C}$

• As Frequency increases, $\omega \uparrow$, $Z \downarrow$, $S_{11} \rightarrow 0$, $S_{21} \rightarrow 1 \Rightarrow$ All power passes through capacitor

• As Frequency decreases, $\omega \downarrow$, $Z \uparrow$, $S_{11} \rightarrow 1$, $S_{21} \rightarrow 0 \Rightarrow$ All power is reflected back

Cascading S-Parameters:

Convert S-matrices into their equivalent T-matrices: $T_{11} = S_{12} - \frac{S_{11}S_{22}}{S_{21}}$, $T_{12} = \frac{S_{11}}{S_{21}}$

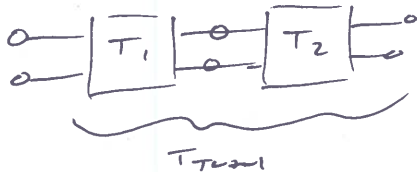
$$\begin{bmatrix} b_1 \\ a_1 \end{bmatrix} = \begin{bmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{bmatrix} \begin{bmatrix} a_2 \\ b_2 \end{bmatrix} \quad \begin{array}{c} a_1 \rightarrow \\ b_1 \leftarrow \end{array} \boxed{S/T} \begin{array}{c} \text{---} \rightarrow b_2 \\ \text{---} \leftarrow a_2 \end{array}$$

Port 1 T Port 2

$$T_{21} = -\frac{S_{22}}{S_{21}}, \quad T_{22} = 1/S_{21}$$

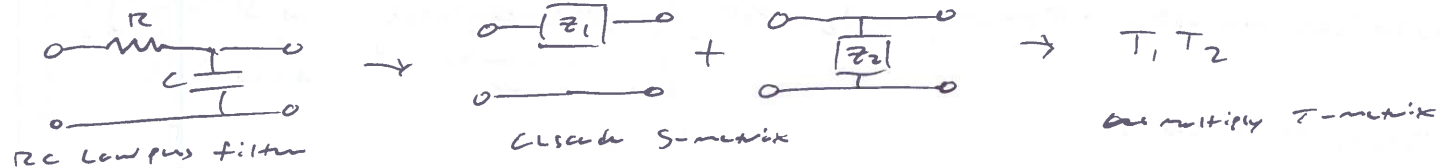
Cascade T-matrix by matrix multiplication:

* Also can use ABCD matrix equivalently.



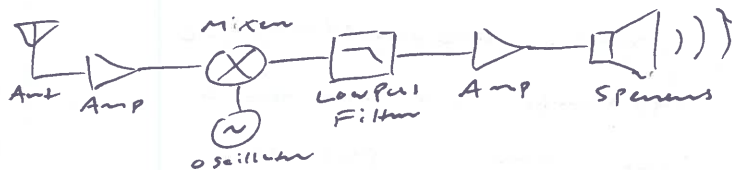
This kind of analysis is what is used in advanced RF/microwave simulation software.

Example:



FM Radio Receiver System (How it works):

Simplified FM Radio Receiver Block Diagram



• We could represent each component as an S-matrix and cascade using T-matrix.

• But since this is an ideal system we can approximate that it is Unidirectional and use simple functions,

$$X \rightarrow \boxed{f} \rightarrow f(X)$$

Define abstract component functions:

Antenna (source)

Amplifier

Oscillator (source)

$$\begin{array}{c} \text{Antenna (source)} \\ \text{---} \end{array} \rightarrow V(t) = V_0 e^{j\omega t}$$

$$V_0 e^{j\omega(t)t} \rightarrow \boxed{\text{Amp}} \rightarrow G V_0 e^{j\omega(t)t}$$

$$\text{Oscillator (source)} \rightarrow V_0 e^{j\omega_0 t}$$

Lowpass Filter

$$V_0 e^{j\omega t} \rightarrow \boxed{W_c} \rightarrow \begin{cases} V_0 e^{j\omega t}, & \omega < W_c \\ 0, & \omega > W_c \end{cases}$$

Mixer

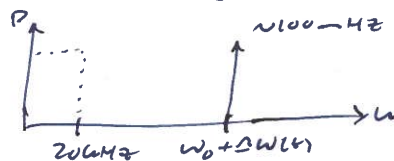
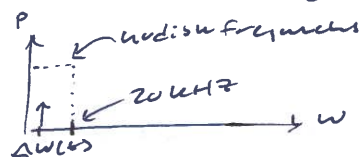
$$X \rightarrow \boxed{\otimes} \rightarrow f(X, Y) = \text{Re}\{X\} \text{Re}\{Y\}$$

$X \sim e^{j\omega t}$
 $Y \sim e^{j\omega_0 t}$

FM Radio consists of a high frequency carrier signal ($\sim 100\text{ MHz}$) that has its frequency modulated slightly over time with an audio signal

Audio Signal $\sim \cos(\Delta W(t)t)$

FM Signal $\sim \cos(W_0 t + \Delta W(t)t)$

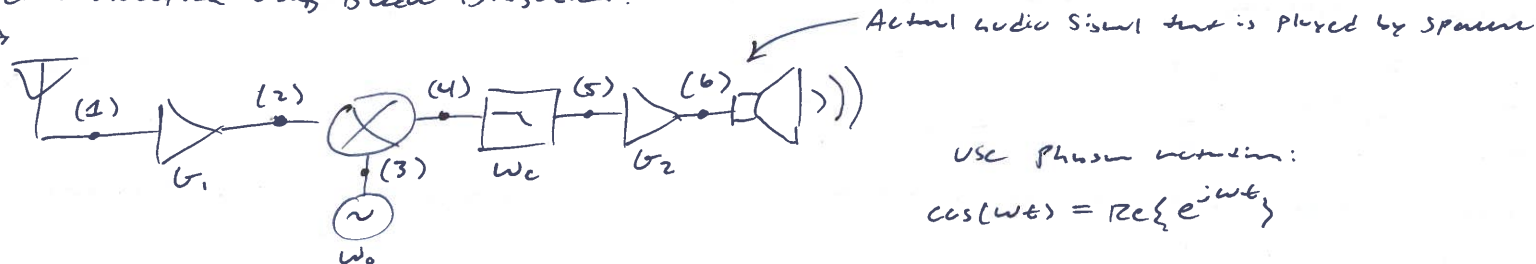


$W_0 \sim 100\text{ MHz}$
 $\Delta W(t) \sim 10\text{ kHz}$
 $W_0 \gg \Delta W(t)$

The FM Radio Receiver needs to downconvert the FM signal by reversing the carrier frequency, W_0 , and bring the audio signal back to the audible range.

Demonstration using Block Diagram:

⚡



USE Phasor notation:

$$\cos(Wt) = \text{Re}\{e^{jWt}\}$$

(1) $V(t) = V_0 \cos((W_0 + \Delta W(t))t)$

(2) $G_1 V_0 \cos((W_0 + \Delta W(t))t)$

(3) $V_1 \cos(W_0 t)$

(4) $G_1 V_0 \cos((W_0 + \Delta W(t))t) \cdot V_1 \cos(W_0 t) = \frac{1}{2} G_1 V_0 V_1 (\underbrace{\cos((2W_0 + \Delta W(t))t)}_{\text{High frequency}} + \underbrace{\cos(\Delta W(t)t)}_{\text{Audio signal}})$

(5) $\frac{1}{2} G_1 V_0 V_1 \cos(\Delta W(t)t)$

(6) $\frac{1}{2} G_2 G_1 V_0 V_1 \cos(\Delta W(t)t)$ ✓ Done!

⬆
Audio recovered

Now that we have designed an FM Radio System architecturally, we must now build its individual components separately, and attempt to optimize them to be as close to their ideal forms as possible.